

Hamilton - Jacobi Method

Hamilton's Principal Function

Action $S = \int_{t_1}^{t_2} dt L(q(t), \dot{q}(t), t)$

We treat $S[q(t), \dot{q}(t), t]$ as a "functional"
of functions $q(t), \dot{q}(t)$

Requiring $\delta S = 0$ subject to $q(t_1) = q_1$,
 $q(t_2) = q_2$ held fixed, gives Euler-Lagrange

eqn.s $-\frac{d}{dt} \left(\frac{\delta L}{\delta \dot{q}} \right) + \frac{\delta L}{\delta q} = 0$



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Let $q_{EL}(t)$ be the solution of E-L eqn.s

And let

$$S(q_f, t_f) = \int_{t_1}^{t_f} L(q_{EL}(t'), \dot{q}_{EL}(t'), t') dt'$$

This object is called Hamilton's Principal function and is an ordinary function of endpoint value q_f at time t_f

Question? What is $\partial S / \partial q_f$

$$\delta S = \int_{t_1}^{t_f} dt \left(\frac{\partial L}{\partial \dot{q}} \delta \dot{q} + \frac{\partial L}{\partial q} \delta q \right)$$



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$$\therefore \delta S = \left. \frac{\delta L}{\delta \dot{q}} \delta q \right|_{t_1}^{t_f} + \int_{t_1}^{t_f} dt \underbrace{\left(-\frac{d}{dt} \left(\frac{\delta L}{\delta \dot{q}} \right) + \frac{\delta L}{\delta q} \right)}_{=0} \delta q$$

Now set $q = q_{EL} \rightarrow = 0$

$$\delta S = \left. \frac{\delta L}{\delta \dot{q}} \delta q \right|_{t_f} \quad \text{ie} \quad \frac{\partial S}{\partial q} = p$$

S is different from $S[q(t), \dot{q}(t)]$

What is $\frac{\partial S}{\partial t}$? Note

$$L = \frac{dS}{dt} = \frac{\partial S}{\partial q} \dot{q} + \frac{\partial S}{\partial t} \cancel{\dot{t}}$$

Thus

$$\begin{aligned}\frac{\partial S}{\partial t} &= L - \frac{\partial S}{\partial q} \dot{q} = L - p \dot{q} \\ &= -H(q_f, p_f, t_f)\end{aligned}$$

$$\frac{\partial S}{\partial t} + H(q, \frac{\partial S}{\partial q}, t) = 0$$

Hamilton - Jacobi equation

For H indep. of t , energy is conserved, and

in fact, $H = E$

In this case we can write

$$S = W(q) - Et$$



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Canonical transformations

These are transformations

$$Q_i = Q_i(q_j, p_j, t)$$

$$P_i = P_i(q_j, p_j, t)$$

s.t. new variables Q_i, P_i solve also the canonical equations with corresponding transformed Hamiltonian K

$$\frac{\partial H}{\partial q_i} = -\dot{p}_i ; \quad \frac{\partial H}{\partial p_i} = \dot{q}_i \quad \parallel \quad \frac{\partial K}{\partial Q_j} = -\dot{P}_j ; \quad \frac{\partial K}{\partial P_j} = \dot{Q}_j$$



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Since both must satisfy dynamics
i.e. Hamilton's Principle of least action,

$$\delta \int \left\{ \sum P_i \dot{Q}_i - K(Q_i, P_i, t) \right\} dt = 0$$

$$= \delta \int \left\{ \sum p_i \dot{q}_i - H(q_i, p_i, t) \right\} dt$$

i.e. $\sum P_i dQ_i - K dt = \sum p_i dq_i - H dt - dF,$

i.e. the differentials differ at most by an
exact differential $dF,$

(Note $\int_i^f \frac{dF}{dt} dt = F_f - F_i$
 $\therefore \delta \int \frac{dF}{dt} dt = 0$)



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Thus, we observe,

$$dF_1 = \sum p_i dq_i - \sum P_i dQ_i + (-H + K) dt$$

Compare $dF_1 = \sum \frac{\partial F_1}{\partial q_i} dq_i + \sum \frac{\partial F_1}{\partial Q_i} dQ_i$
 $+ \frac{\partial F_1}{\partial t}$

$$\therefore \begin{aligned} p_i &= \frac{\partial F_1}{\partial q_i} \\ P_i &= -\frac{\partial F_1}{\partial Q_i} \\ K &= \frac{\partial F_1}{\partial t} + H \end{aligned}$$

If we solve for F_1 ,
from there we have
the "generators" of the
required transf.



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The last eqn. is suspiciously similar to H-J eqn. if we demand $K=0$

But $F_1(q_i; Q_i)$ whereas $S(q_i; p_i)$

Thus actually we need a generator which is a function of $q_i; P_i$

$$\text{Let } F_2(q_i; P_i) = F_1(q_i; Q_i) + \sum Q_i P_i$$

$$\text{Then } dF_2 = \sum_i \left\{ \frac{\partial F_1}{\partial q_i} dq_i + \underbrace{\frac{\partial F_1}{\partial Q_i} dQ_i + P_i dQ_i + Q_i dP_i}_{=0} \right\}$$



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Then we find

$$P_i = \frac{\partial F_2}{\partial \dot{q}_i}$$

$$Q_i = \frac{\partial F_2}{\partial P_i}$$



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Thus we can argue that H-J eqn. can be solved by a canonical transf. of type F_2

$$\frac{\partial S}{\partial t} + H\left(q_i, \frac{\partial S}{\partial q_i}, t\right) = 0$$

Suppose we find a solution

$$S = f(t, q_1, \dots, q_n; \alpha_1, \dots, \alpha_n) + A$$

Treat f as if it is F_2 with the integration constants α_j to be P_j

Then we should have

$$P_j = \frac{\partial f}{\partial q_j} \quad \& \quad \beta_j = \frac{\partial f}{\partial \alpha_j}$$

... β_j are "new co-ord.s"

$$K = H + \frac{\partial f}{\partial t} = 0 \quad \dots \text{since } f \text{ solves } H-J \text{ eqn.}$$

Thus, we use n first order eqn.s

$$\frac{\partial f}{\partial \alpha_j}(q_j, \alpha_j) = \beta_j$$

Inverting the solutions we know $q_j(\alpha_j, \beta_j, t)$



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And we know $p_i = \frac{\partial f}{\partial q_i}$

Conclusions:

1. H-J equation is a first order equation with a strong resemblance to Schrödinger eqn.
2. Its solution $S(q, t)$ is actually a canonical transf. of type F_2 .
2 a) S is generator of time evolution "transf."
3. Thus in QM $e^{iAS/\hbar}$ is the time evolution



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unitary transt. for small ΔS

4. We learnt that for arbitrary $t_i, t_f,$

$$\langle q_f, t_f | q_i, t_i \rangle_{\Delta} = \sum_{\text{paths}} e^{i S(\text{path})/\hbar}$$



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